

BREAKING 10^9 RAYS/SEC

IAN MALLET



BREAKING 10^{14} KEYS/SEC
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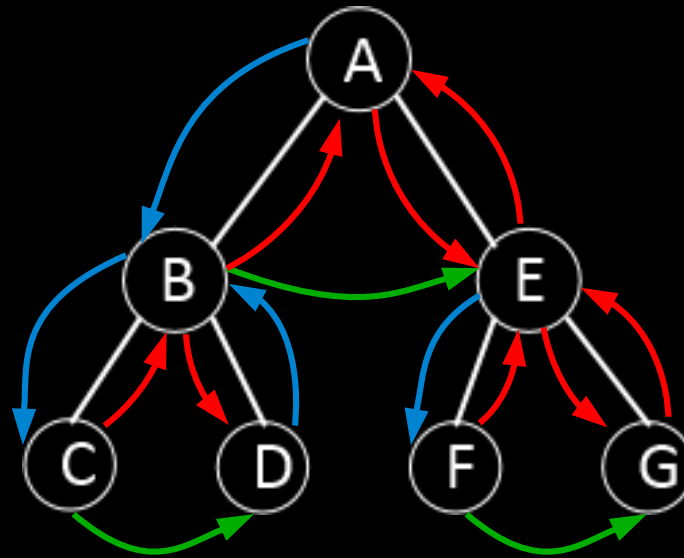
MISSION ACCOMPLISHED

Overview

- Lots of fancy optimizations & lots of challenges
- Finished “idea 1” from original proposal: the stack-based scene-caching thing
- Gotten 1,000,000,000 rays/second with reasonably sized chip! Mission accomplished?

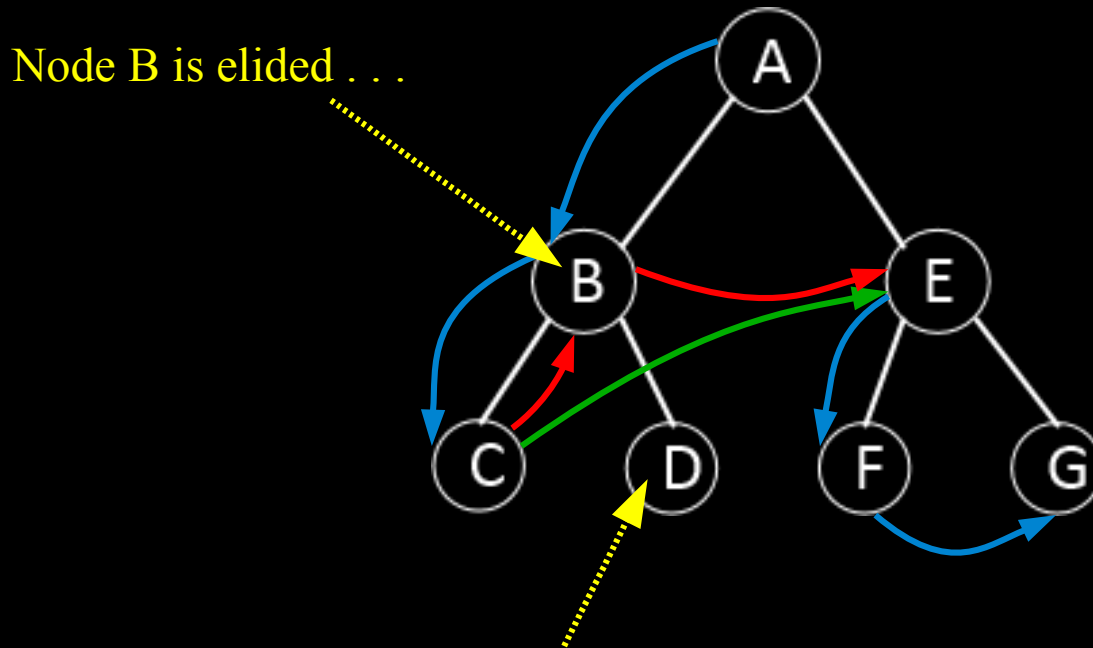
Important Optimizations

- Sidestep traversal (skip parent nodes)



Important Optimizations

- Elision of nodes where only one child hit in traversal (subtract one from depth of later nodes)



. . . since in this traversal,
node D's bounding box
didn't intersect the ray.

Important Optimizations

- Miscellaneous other for BVH:
 - Miscellaneous mentioned last time
 - Faster ray/box intersection
 - Nearest first & early termination
 - Non-recursive traversal
 - Miscellaneous fancy unmentioned stuff
 - Triangle edges, not verts
 - Relative pointers (TODO?)
 - Special shadow ray traversal (TODO)

Important Optimizations

- Impact of optimizations:
 - Recursive (and so no sidestep or elision):
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 - Nonrecursive (with sidestep and elision):
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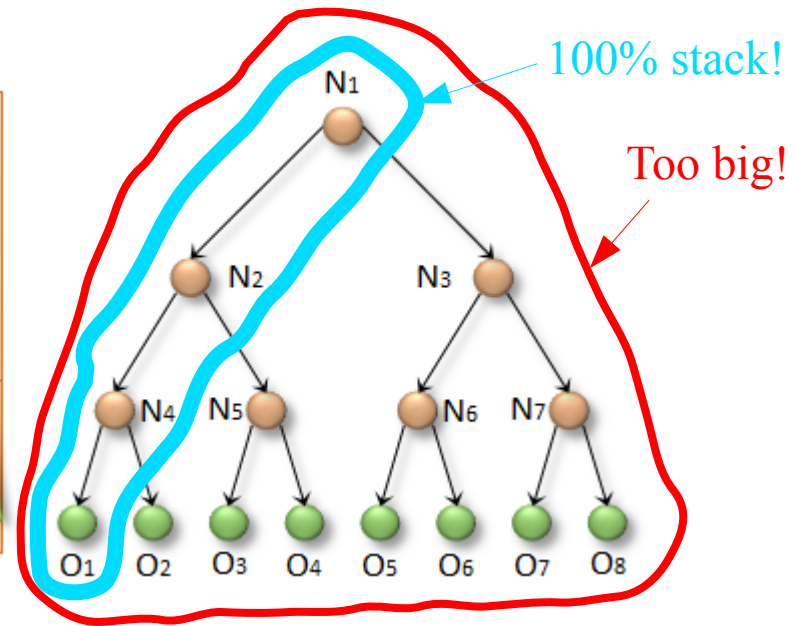
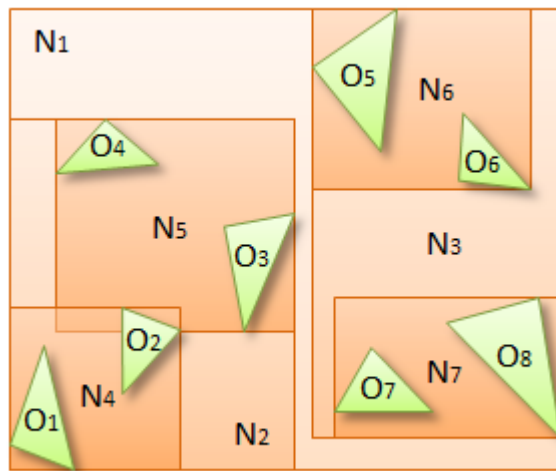
Important Optimizations

- Miscellaneous micro-optimization
 - Not sorry about this. Worth it.
- Sometimes didn't play nicely with compiler / simulator . . .
 - Placement new, std:: library stuff
 - Unimplemented instructions
 - Cycle counter
 - Danny fixes all! Thanks!

Challenges

- Pointer arithmetic nightmare!
- Concurrent deletion within thread (i.e., node A's load triggers a delete, which requires node A to move within memory)
- Deletion in general (surprisingly difficult algorithm!)
- Implementation issues
- Slow compiles/runs (esp. larger scenes)
- EGSR paper deadline
- Ran out of coffee

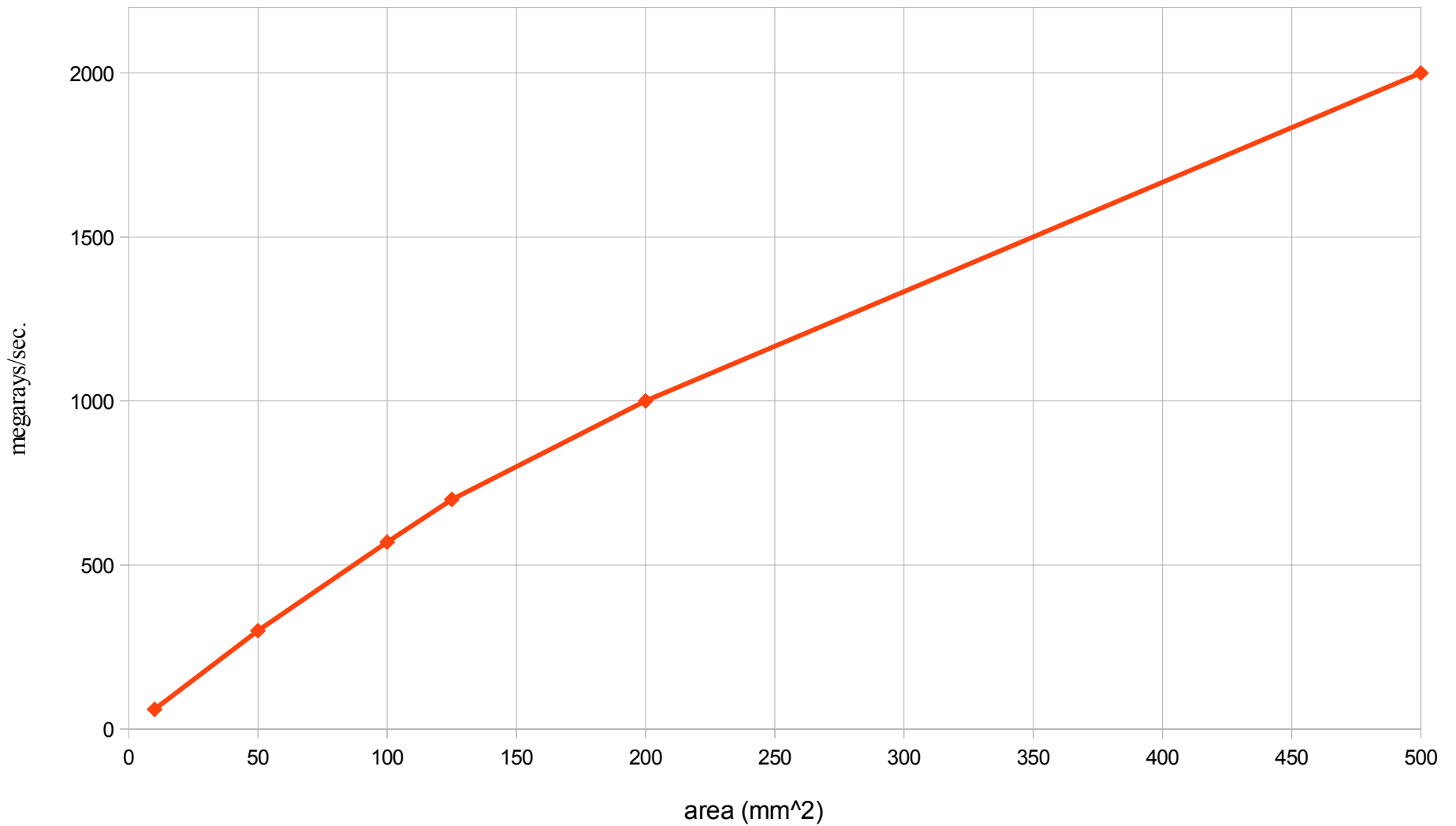
Finished Idea 1 of 3!



The Performance/Area Graph

- Main result: broke 10^9 rays/second with reasonably sized chip on decently sized dynamically-loaded scene (conference)
- Hand-generated some configurations to produce performance vs. area graph (next page)

The Performance/Area Graph



TODO

- Now what? Remaining (original) two ideas:
 - 2: Bitmap coarse-traversal
 - Traversal is already ludicrously complicated. Well, *very*, anyway.
 - Requires hacking BVH building. Thoughts?
 - 3: Ray rescheduling (req. 2) (was “stretch goal”)
- Still have room for optimization
 - Ray packets
 - Other datastructure (I changed node size)
- New ideas? 10^{10} rays/second???

Questions?

Image Credits

- <http://bryanwagstaff.com/wp-content/uploads/2013/10/d>
- <http://childrenshungerfund.org/missiondh/images/mission>
- me
- other?